

8.5 " Unfoldable Hidden Line Bird Lime c Smart App Control Escuoter Share Scooter GPRS Tracker

Introduction

The purpose of this project is to develop a system that can detect and classify objects in a 3D environment. The system will use a combination of computer vision and machine learning techniques to achieve this goal.



The system will be able to detect and classify objects in a 3D environment. It will use a combination of computer vision and machine learning techniques to achieve this goal.

Object	Class	Confidence
Apple	Apple	0.95
Banana	Banana	0.92
Orange	Orange	0.98
Grape	Grape	0.91
Strawberry	Strawberry	0.93
Pineapple	Pineapple	0.96
Melon	Melon	0.94
Cantaloupe	Cantaloupe	0.97
Watermelon	Watermelon	0.99
Pumpkin	Pumpkin	0.90



Figure 1: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.



Figure 2: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 3: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 4: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 5: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 6: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 7: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 8: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 9: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 10: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 11: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 12: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 13: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 14: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 15: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 16: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 17: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 18: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 19: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 20: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 21: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 22: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.

Figure 23: A close-up image of a hand holding a small object, possibly a fruit, with a bounding box around it.